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Inventor Information for 10/644796

Inventor Name	City	State/Country
KIM, MUN-SANG	SEOUL	KOREA, REPUBLIC OF
KIM, JOONG-HAN	SEOUL	KOREA, REPUBLIC OF

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US 20050110758 A1	20050526	15	Tactile mouse interface system	345/163		Kyung, Ki Uk et al.
US 20050075585 A1	20050407		Apparatus and method for measuring jaw motion	600/590		Kim, Mun- Sang et al.
US 20030216821 A1	20031120		Apparatus for measuring and fixing the three- dimensional location of medical instrument	700/56		Kim, Mun Sang et al.
US 20030090115 A1	20030515	22	Robot hand and robot hand finger	294/106		Kim, Mun- Sang et al.
US 20030047230 A1	20030313		Apparatus for ligating wires	140/119		Kim, Joong-han
US 20030044745 A1	20030306		Anchor implanting device for orthodontics	433/4	433/173; 433/18	Kim, Joong-han
US 20010018175 A1	20010830		Orthodontic jig for attaching orthodontic brackets	433/4	433/3	Kim, Joong Han
US 7020542 B2	20060328		Apparatus for measuring and fixing the three- dimensional location of medical instrument	700/245	318/568.11; 318/568.13; 318/568.16; 318/568.2; 700/131; 700/250; 700/251; 700/257; 700/258; 700/259; 700/260; 701/10; 701/23; 701/26; 901/1	Kim; Mun Sang et al.
US 6918622 B2	20050719		Robot hand and robot hand finger	294/106	294/907; 901/34; 901/38	Kim; Mun- Sang et al.
US 6890174 B2	20050510		Anchor implanting device for orthodontics	433/18	433/173	Kim; Joong-han

US 6447291 B2	20020910		Orthodontic jig for attaching orthodontic brackets	433/4	433/24; 606/211	Kim; Joong Han
US 6301526 B1	20011009		Master device having force reflection function	700/260	600/1; 600/109; 600/118; 600/559; 606/130; 700/245; 700/248; 700/257; 700/262; 700/263; 700/264; 74/490.01; 74/490.02; 74/490.03; 74/490.05; 74/490.06; 901/27; 901/28; 901/3; 901/30; 901/34; 901/36	Kim; Mun Sang et al.
US 5868787 A	19990209		Orthodontic tweezers with a gauge	606/211	606/210	Kim; Joong Han
US 5400638 A	19950328		Calibration system for compensation of arm length variation of an industrial robot due to peripheral temperature change	73/1.79		Kim; Mun Sang